Product datasheet

Specifications





variable speed drive, Altivar Machine ATV320, 0.55kW, 200 to 240V, 1 phase, book

ATV320U06M2B

Main

Range of product	Altivar Machine ATV320
Product or component type	Variable speed drive
Product specific application	Complex machines
variant	Standard version Standard version
Format of the drive	Book
mounting mode	Cabinet mount
Communication port protocol	Modbus serial CANopen
Option card	Communication module, CANopen Communication module, EtherCAT Communication module, Profibus DP V1 Communication module, PROFINET Communication module, Ethernet Powerlink Communication module, EtherNet/IP Communication module, DeviceNet
[Us] rated supply voltage	200240 V - 1510 %
Nominal output current	3.7 A
Motor power kW	0.55 kW for heavy duty
EMC filter	Class C2 EMC filter integrated
IP degree of protection	IP20

Complementary

Discrete input number	7
Discrete input type	STO safe torque off, 24 V DC, impedance: 1.5 kOhm
	DI1DI6 logic inputs, 24 V DC (30 V)
	DI5 programmable as pulse input: 030 kHz, 24 V DC (30 V)
Discrete input logic	Positive logic (source)
	Negative logic (sink)
Discrete output number	3
Discrete output type	Open collector DQ+ 01 kHz 30 V DC 100 mA
	Open collector DQ- 01 kHz 30 V DC 100 mA
Analogue input number	3
Analogue input type	Al1 voltage: 010 V DC, impedance: 30 kOhm, resolution 10 bits
	Al2 bipolar differential voltage: +/- 10 V DC, impedance: 30 kOhm, resolution 10 bits
	Al3 current: 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by
	configuration), impedance: 250 Ohm, resolution 10 bits
Analogue output number	1

Price is "List Price" and may be subject to a trade discount – check with your local distributor or retailer for actual price.

Analogue output type	Software-configurable current AQ1: 020 mA impedance 800 Ohm, resolution 10 bits Software-configurable voltage AQ1: 010 V DC impedance 470 Ohm, resolution 10 bits
Relay output type	Configurable relay logic R1A 1 NO electrical durability 100000 cycles Configurable relay logic R1B 1 NC electrical durability 100000 cycles Configurable relay logic R1C Configurable relay logic R2A 1 NO electrical durability 100000 cycles Configurable relay logic R2C
Maximum switching current	Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V DC
Minimum switching current	Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC
Method of access	Slave CANopen
4 quadrant operation possible	True
Asynchronous motor control profile	Voltage/frequency ratio, 5 points Flux vector control without sensor, standard Voltage/frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor - Energy Saving Voltage/frequency ratio, 2 points
Synchronous motor control profile	Vector control without sensor
Fransient overtorque	170200 % of nominal motor torque
Maximum output frequency	0.599 kHz
Acceleration and deceleration ramps	Linear U S CUS Ramp switching Acceleration/deceleration ramp adaptation Acceleration/deceleration automatic stop with DC injection
Motor slip compensation	Automatic whatever the load Adjustable 0300 % Not available in voltage/frequency ratio (2 or 5 points)
Switching frequency	216 kHz adjustable 416 kHz with derating factor
Nominal switching frequency	4 kHz
Braking to standstill	By DC injection
Brake chopper integrated	True
Line current	7.9 A at 200 V (heavy duty) 6.7 A at 240 V (heavy duty)
Maximum input current	7.9 A
Maximum output voltage	240 V
Apparent power	1.6 kVA at 240 V (heavy duty)
network frequency	5060 Hz
Relative symmetric network requency tolerance	5 %
Prospective line Isc	1 kA
Base load current at high overload	66.0 A
Power dissipation in W	Fan: 35.0 W at 200 V, switching frequency 4 kHz
With safety function Safely Limited Speed (SLS)	True

With safety function Safe brake management (SBC/SBT) With safety function Safe Operating Stop (SOS) With safety function Safe Position (SP) With safety function Safe Position (SP) With safety function Safe programmable logic With safety function Safe Speed Monitor (SSM) With safety function Safe Stop 1 (SS1) With safety function Safe Stop 1 (True (SS1)) With safety function Safe Stop 2 (SS2) With safety function Safe torque off (STO) With safety function Safe torque off (STO) With safety function Safely Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm Depth 245.0 mm		
Operating Stop (SOS) With safety function Safe Position (SP) With safety function Safe programmable logic With safety function Safe Speed Monitor (SSM) With safety function Safe Stop 1 True (SS1) With safety function Safe Stop 2 (SS2) False With safety function Safe torque off (STO) With safety function Safe torque off (STO) With safety function Safe by False With safety function Safe by False With safety function Safe by False United Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overcurrent between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		False
With safety function Safe programmable logic With safety function Safe Speed Monitor (SSM) With safety function Safe Stop 1 True (SS1) With safety function Safe Stop 2 (SS2) With safety function Safe torque off (STO) With safety function Safety Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overcurrent between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		False
programmable logic With safety function Safe Speed Monitor (SSM) With safety function Safe Stop 1 True (SS1) With safety function Safe Stop 2 (SS2) False With safety function Safe torque off (STO) With safety function Safely Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overcheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		False
Monitor (SSM) With safety function Safe Stop 1 (SS1) With sft fct Safe Stop 2 (SS2) With safety function Safe torque off (STO) With safety function Safety Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		False
With safety function Safe torque off (STO) With safety function Safe torque off (STO) With safety function Safely Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		False
With safety function Safe torque off (STO) With safety function Safely Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		True
off (STO) With safety function Safely Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm	With sft fct Safe Stop 2 (SS2)	False
Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		True
Direction (SDI) Protection type Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		False
Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive Width 45.0 mm Height 325.0 mm		False
Height 325.0 mm	Protection type	Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive
	Width	45.0 mm
Depth 245.0 mm	Height	325.0 mm
	Depth	245.0 mm
Net weight 2.4 kg	Net weight	2.4 kg

Environment

Operating position	Vertical +/- 10 degree
Product certifications	CE
	ATEX
	NOM
	GOST
	EAC
	RCM
	KC
marking	CE
	ATEX
	UL
	CSA
	EAC
	RCM
Standards	IEC 61800-5-1
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3
	Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4
	1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5
	Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
	Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Environmental class (during	Class 3C3 according to IEC 60721-3-3
operation)	Class 3S2 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 213 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3

Volume of cooling air	9.4 m3/h
Overvoltage category	III
Regulation loop	Adjustable PID regulator
Speed accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn
Pollution degree	2
Ambient air transport temperature	-2570 °C
Ambient air temperature for operation	-1050 °C without derating 5060 °C with derating factor
Ambient air temperature for storage	-2570 °C

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	8.500 cm
Package 1 Width	27.500 cm
Package 1 Length	32.500 cm
Package 1 Weight	2.251 kg
Unit Type of Package 2	P06
Number of Units in Package 2	24
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	67.024 kg



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Transparency RoHS/REACh

Resource performance



Upgraded Components Available

Well-being performance



Mercury Free



Rohs Exemption Information

Yes

Certifications & Standards

Reach Regulation	REACh Declaration
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)
China Rohs Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
Circularity Profile	End of Life Information

Product datasheet

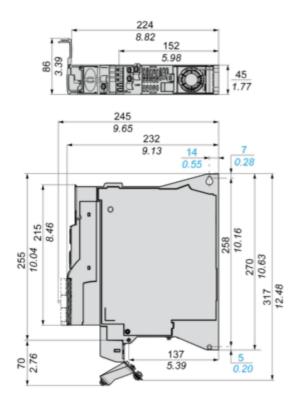
ATV320U06M2B

Dimensions Drawings

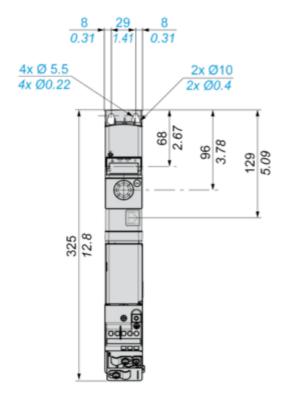
Dimensions

Bottom, Right and Front View

mm in.



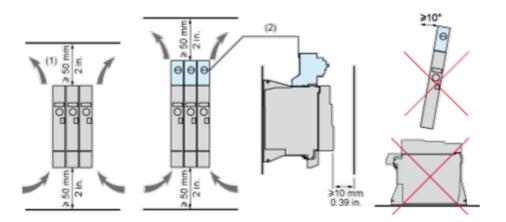
 $\frac{\text{mm}}{\text{in.}}$



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Mounting and Clearance

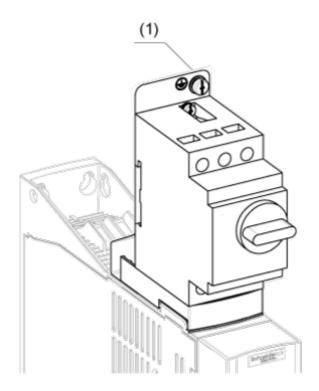
Mounting and Clearance



- (1) Minimum value corresponding to thermal constraints. (2) Optional GV2 circuit-breaker

Option: Protection Device, GV2 circuit-breaker

NOTE: The product overall height dimension, including GV2 adapter and EMC plate mounted, becomes 424 mm (16.7 in.) instead of 325 mm (12.80 in.)



(1) Ground screw (HS type 2 - 5x12)

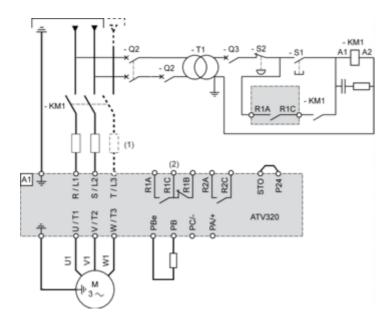
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Connections and Schema

Connection Diagrams

Diagram with Line Contactor

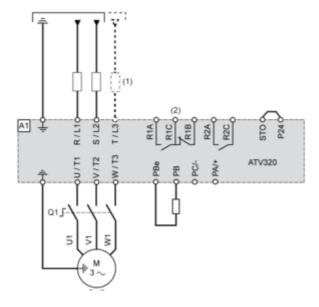
Connection diagrams conforming to standards ISO13849 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) Fault relay contacts, for remote signaling of drive status

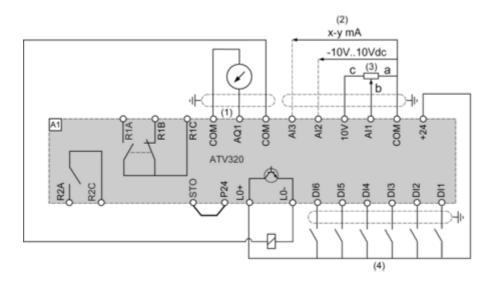
Diagram with Switch Disconnect

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) Fault relay contacts, for remote signaling of drive status

Control Connection Diagram in Source Mode



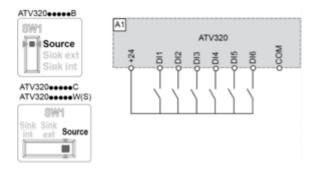
- (1) Analog output
- (2) Analog inputs
- (3) Reference potentiometer (10 kOhm maxi)
- (4) Digital inputs

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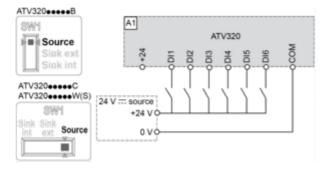
Digital Inputs Wiring

The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

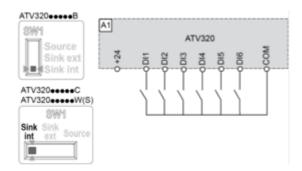
Switch SW1 set to "Source" position and use of the output power supply for the DIs.



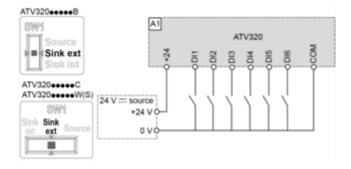
Switch SW1 set to "Source" position and use of an external power supply for the DIs.



Switch SW1 set to "Sink Int" position and use of the output power supply for the DIs.



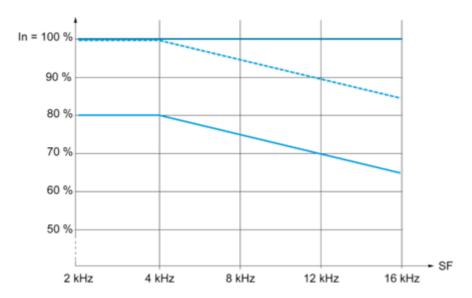
Switch SW1 set to "Sink Ext" position and use of an external power supply for the Dls.



Performance Curves

Derating Curves

Derating curve for the nominal drive current (In) as a function of temperature and switching frequency (SF).



40 °C (104 °F) - Mounting type A, B and C 50 °C (122 °F) - Mounting type A, B and C 60 °C (140 °F) - Mounting type B and C

In: Nominal Drive Current SF: Switching Frequency