Specifications





# variable speed drive, Altivar Machine ATV340, 0.75kW, heavy duty, 400V, 3 phases, Ethernet

ATV340U07N4E

Product availability: Stock - Normally stocked in distribution facility

#### Price\*: 960.48 USD

### Main

Range of Product	Altivar Machine ATV340
Product or Component Type	Variable speed drive
Product Specific Application	Machine
variant	Standard version
Mounting Mode	Cabinet mount
Communication Port Protocol	Modbus TCP Modbus serial EtherNet/IP
Phase	3 phase
Supply frequency	5060 Hz +/- 5 %
[Us] rated supply voltage	380480 V - 1510 %
Nominal output current	2.2 A
Motor power kW	1.1 kW normal duty 0.75 kW heavy duty
Maximum Horse Power Rating	1.5 hp normal duty 1 hp heavy duty
EMC filter	Class C3 EMC filter integrated
IP degree of protection	IP20

## Complementary

Discrete input number	5		
Discrete input type	PTI programmable as pulse input 030 kHz, 24 V DC 30 V) DI1DI5 safe torque off, 24 V DC 30 V)3.5 kOhm programmable		
number of preset speeds	16 preset speeds	16 preset speeds	
Discrete output number	2.0		
Discrete output type	Programmable output DQ1, DQ2 30 V DC 100 mA		
Analogue input number	2		
Analogue input type	Al1 software-configurable current 020 mA 250 Ohm 12 bits Al1 software-configurable temperature probe or water level sensor Al1 software-configurable voltage 010 V DC 31.5 kOhm 12 bits Al2 software-configurable voltage - 1010 V DC 31.5 kOhm 12 bits		
Analogue output number	1		
Analogue output type	Software-configurable voltage AQ1 010 V DC 470 Ohm 10 bits Software-configurable current AQ1 020 mA 500 Ohm 10 bits		

Price is "List Price" and may be subject to a trade discount - check with your local distributor or retailer for actual price.

Relay output number	2	
Output voltage	<= power supply voltage	
Relay output type	Relay outputs R1A Relay outputs R1C 100000 cycles Relay outputs R2A Relay outputs R2C 100000 cycles	
Maximum switching current	Relay output R1C resistive, cos phi = 1 3 A 250 V AC Relay output R1C resistive, cos phi = 1 3 A 30 V DC Relay output R1C inductive, cos phi = 0.4 7 ms 2 A 250 V AC Relay output R1C inductive, cos phi = 0.4 7 ms 2 A 30 V DC Relay output R2C resistive, cos phi = 1 5 A 250 V AC Relay output R2C resistive, cos phi = 1 5 A 30 V DC Relay output R2C resistive, cos phi = 1 5 A 30 V DC Relay output R2C inductive, cos phi = 0.4 7 ms 2 A 250 V AC Relay output R2C inductive, cos phi = 0.4 7 ms 2 A 250 V AC	
Minimum switching current	Relay output R1B 5 mA 24 V DC Relay output R2C 5 mA 24 V DC	
Physical interface	2-wire RS 485	
Connector Type	3 RJ45	
Method of access	Slave Modbus RTU Slave Modbus TCP	
Transmission Rate	4.8 kbit/s 9.6 kbit/s 19.2 kbit/s 38.4 kbit/s	
Transmission frame	RTU	
Number of addresses	1247	
Data format	8 bits, configurable odd, even or no parity	
Type of polarization	No impedance	
4 quadrant operation possible	True	
Asynchronous motor control profile	Constant torque standard Variable torque standard Optimized torque mode	
Synchronous motor control profile	Reluctance motor Permanent magnet motor	
Pollution degree	2 IEC 61800-5-1	
Maximum output frequency	0.599 kHz	
Acceleration and deceleration ramps	S, U or customized Linear adjustable separately from 0.019999 s	
Motor slip compensation	Automatic whatever the load Adjustable Not available in permanent magnet motor law Can be suppressed	
Switching frequency	216 kHz adjustable 1416 kHz with derating factor	
Nominal switching frequency	4 kHz	
Braking to standstill	By DC injection	
Brake chopper integrated	True	
Line current	2.6 A 380 V normal duty) 2.1 A 480 V normal duty) 3.4 A 380 V heavy duty) 2.6 A 480 V heavy duty)	

True	

Protection type	Thermal protection motor		
	Safe torque off motor		
	Motor phase loss motor		
	Thermal protection drive		
	Safe torque off drive		
	Overheating drive		
	Overcurrent drive		
	Output overcurrent between motor phase and earth drive		
	Output overcurrent between motor phases drive		
	Short-circuit between motor phase and earth drive		
	Short-circuit between motor phases drive		
	Motor phase loss drive		
	DC Bus overvoltage drive		
	Line supply overvoltage drive		
	Line supply undervoltage drive		
	Input supply loss drive		
	Exceeding limit speed drive		
	Break on the control circuit drive		
Width	3.3 in (85.0 mm)		
Height	10.6 in (270.0 mm)		
Depth	9.2 in (232.5 mm)		
Net Weight	3.7 lb(US) (1.7 kg)		
Continuous output current	2.2 A 4 kHz heavy duty		
	2.8 A 4 kHz normal duty		

### Environment

Operating altitude	<= 9842.52 ft (3000 m) with current derating above 1000m	
Operating position	Vertical +/- 10 degree	
Product Certifications	UL CSA TÜV EAC	
	CTick	
Marking	CE	
Standards	IEC 61800-3 IEC 61800-5-1 IEC 60721-3 IEC 61508 IEC 13849-1 UL 618000-5-1 UL 508C	
Assembly style	With heat sink	
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 IEC 61000-4-5 Conducted radio-frequency immunity test level 3 IEC 61000-4-6	
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3	
Maximum acceleration under shock impact (during operation)	70 m/s² at 22 ms	
Maximum acceleration under vibrational stress (during operation)	5 m/s² at 9200 Hz	
Maximum deflection under vibratory load (during operation)	1.5 mm at 29 Hz	
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3	
Volume of cooling air	4755.2 Gal/hr(US) (18.0 m3/h)	
Type of cooling	Forced convection	
Overvoltage category	Class III	

Regulation loop	Adjustable PID regulator	
Noise level	52.7 dB	
Pollution degree	2	
Ambient air transport temperature	-40.000000000158.0000000000 °F (-4070 °C)	
Ambient air temperature for operation	5.000000000122.0000000000 °F (-1550 °C) without derating vertical position) 122.000000000140.0000000000 °F (5060 °C) with derating factor vertical position)	
Ambient Air Temperature for Storage	-40.00000000158.000000000 °F (-4070 °C)	
Isolation	Between power and control terminals	

# Ordering and shipping details

Category	US1CP4B22182
Discount Schedule	CP4B
GTIN	3606480966989
Returnability	Yes
Country of origin	US

# **Packing Units**

-	
Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	4.213 in (10.700 cm)
Package 1 Width	14.764 in (37.500 cm)
Package 1 Length	12.402 in (31.500 cm)
Package 1 Weight	5.478 lb(US) (2.485 kg)
Unit Type of Package 2	P06
Number of Units in Package 2	14
Package 2 Height	29.528 in (75.000 cm)
Package 2 Width	23.622 in (60.000 cm)
Package 2 Length	31.496 in (80.000 cm)
Package 2 Weight	105.359 lb(US) (47.790 kg)

# Sustainability Screen Premium

**Green Premium<sup>TM</sup> label** is Schneider Electric's commitment to delivering products with best-inclass environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO<sub>2</sub> products.

**Guide to assessing product sustainability** is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

Yes

Learn more about Green Premium >

Guide to assess a product's sustainability >



Transparency RoHS/REACh

#### **Resource performance**

Upgraded Components Available

#### Well-being performance

Mercury Free

Rohs Exemption Information

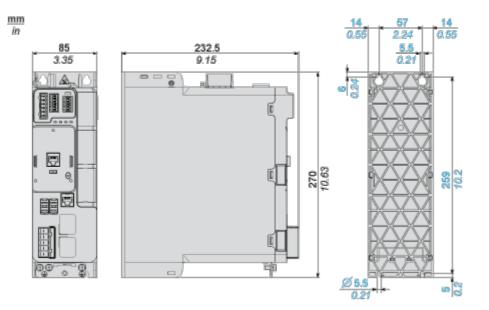
### **Certifications & Standards**

Reach Regulation	REACh Declaration	
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)	
China Rohs Regulation	China RoHS declaration	
Environmental Disclosure	Product Environmental Profile	
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins.	
Weee Circularity Profile		

#### **Dimensions Drawings**

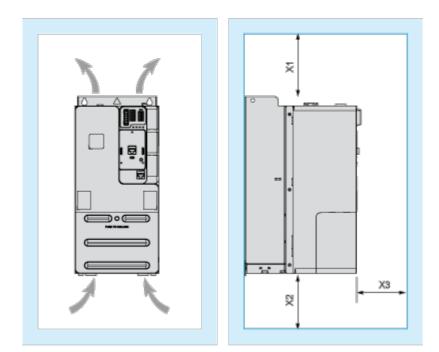
#### Dimensions

#### Views: Front - Left - Rear



Mounting and Clearance

#### Clearance



#### Dimensions in mm

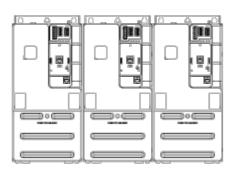
X1	X2	X3
≥ <sub>100</sub>	≥ <sub>100</sub>	≥ <sub>60</sub>

#### Dimensions in in.

X1	X2	Х3
≥ <sub>3.94</sub>	≥ <sub>3.94</sub>	≥ <sub>2.36</sub>

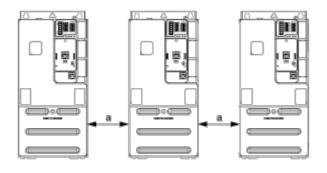
#### Mounting Types

#### Mounting Type A: Side by Side IP20



Possible, at ambient temperature ≤ 50 °C (122 °F)

#### Mounting Type B: Individual IP20



a <sup>≥</sup> 50 mm (1.97 in.) from 50...60°C, no restriction below 50°C

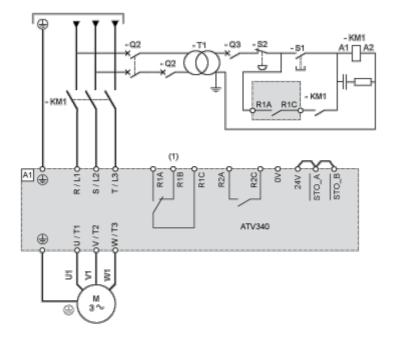
### ATV340U07N4E

#### Connections and Schema

#### **Connections and Schema**

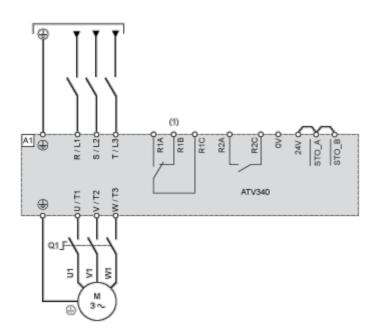
# Three-phase Power Supply with Upstream Breaking via Line Contactor Without Safety Function STO

Connection diagrams conforming to standards ISO13849 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



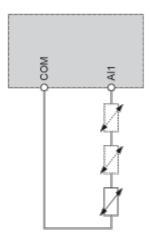
- (1) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.
- A1: Drive
- KM1 : Line Contactor
- Q2, Q3 : Circuit breakers
- S1: Pushbutton
- S2 : Emergency stop
- T1: Transformer for control part

Three-phase Power Supply With Downstream Breaking via Switch Disconnector



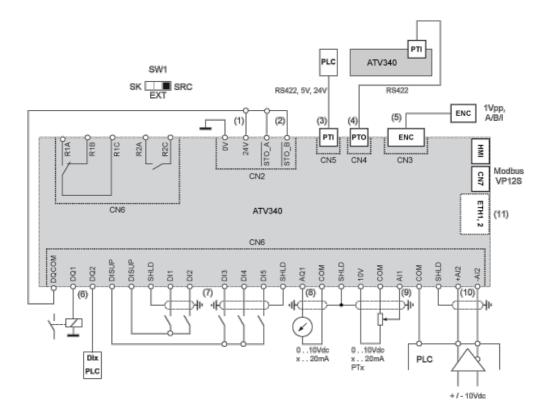
- (1) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.
- A1: Drive
- Q1 : Switch disconnector

#### **Sensor Connection**



It is possible to connect either 1 or 3 sensors on terminals Al1.

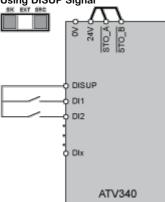
#### **Control Block Wiring Diagram**



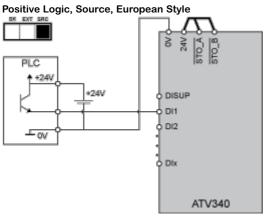
- (1) 24V supply (STO)
- (2) STO Safe Torque Off
- (3) PTI Pulse Train In
- (4) PTO Pulse Train Out
- (5) Motor Encoder connection
- (6) Digital outputs
- (7) Digital inputs
- (8) Analog output
- (9) Analog input
- (10) Differential Analog Input
- (11) Ethernet port (only on Ethernet drive version)
- SW1 : Sink/Source switch
- R1A, R1B, R1C : Fault relay
- R2A, R2C : Sequence relay

#### **Digital Inputs Wiring**

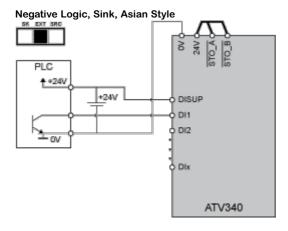
Digital Inputs: Internal Supply Using DISUP Signal



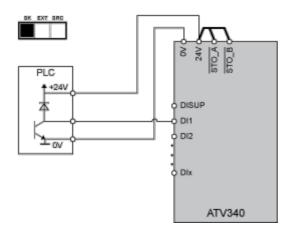
In SRC position DISUP outputs 24 V. In SK position DISUP is connected to 0 V.



#### **Digital Inputs: External Supply**



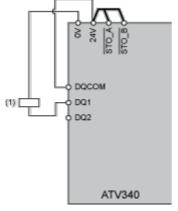
Digital Inputs: Internal supply Negative Logic, Sink, Asian Style



#### **Digital Outputs Wiring**

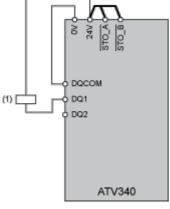
#### Digital Outputs: Internal Supply

Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

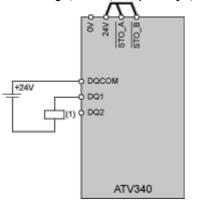
Negative Logic, Sink, Asian Style, DQCOM to 0V



(1) Relay or valve

#### Digital Outputs: External Supply

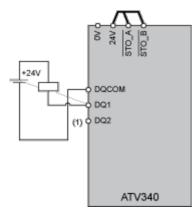
Positive Logic, Source, European Style, DQCOM to +24V



(1) Relay or valve

Negative Logic, Sink, Asian Style, DQCOM to 0V

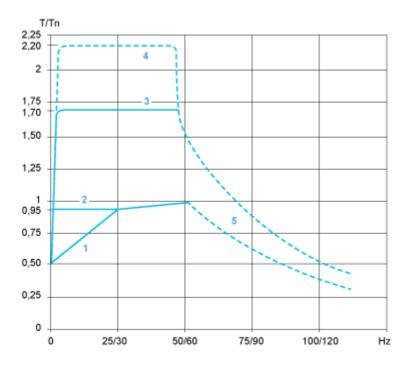
ATV340U07N4E



(1) Relay or valve

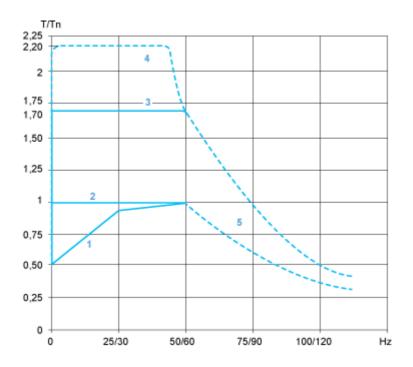
#### Performance Curves

#### **Open Loop Applications**



- 1: Self-cooled motor: continuous useful torque
- 2: Force-cooled motor: continuous useful torque
- 3: Overtorque for 60 s maximum
- 4: Transient overtorque for 2 s maximum
- 5: Torque in overspeed at constant power

#### **Closed Loop Applications**



- 1: Self-cooled motor: continuous useful torque
- 2: Force-cooled motor: continuous useful torque
- 3: Overtorque for 60 s maximum
- 4: Transient overtorque for 2 s maximum
- 5: Torque in overspeed at constant power